

Perfectly β Generalized Continuous Mappings in Intuitionistic Fuzzy Topological Spaces

Saranya M¹ and Jayanthi D²

*Department of Mathematics
Avinashilingam University, Coimbatore, Tamil Nadu, India*

Abstract

In this paper, we introduce intuitionistic fuzzy perfectly β generalized continuous mappings. Furthermore we provide some properties of the same mapping and discuss some fascinating theorems.

Keywords: Intuitionistic fuzzy sets, intuitionistic fuzzy topology, intuitionistic fuzzy β generalized closed sets, intuitionistic fuzzy β generalized continuous mappings, intuitionistic fuzzy perfectly β generalized continuous mappings.

I. INTRODUCTION

Atanassov [1] introduced the idea of intuitionistic fuzzy sets and Coker [2] introduced intuitionistic fuzzy topological spaces using the notion of intuitionistic fuzzy sets. Later this was followed by the introduction of intuitionistic fuzzy β generalized closed sets by Saranya, M and Jayanthi, D [5] in 2016 which was simultaneously followed by the introduction of intuitionistic fuzzy β generalized continuous mappings [7] by the same authors. We now extend our idea towards intuitionistic fuzzy perfectly β generalized continuous mappings and discuss some of their properties.

II. PRELIMINARIES

Definition 2.1 [1]: An *intuitionistic fuzzy set* (IFS for short) A is an object having the form

$$A = \{ \langle x, \mu_A(x), \nu_A(x) \rangle : x \in X \}$$

where the functions $\mu_A : X \rightarrow [0,1]$ and $\nu_A : X \rightarrow [0,1]$ denote the degree of membership (namely $\mu_A(x)$) and the degree of non-membership (namely $\nu_A(x)$) of each element $x \in X$ to the set A , respectively, and $0 \leq \mu_A(x) + \nu_A(x) \leq 1$ for each $x \in X$. Denote by $\text{IFS}(X)$, the set of all intuitionistic fuzzy sets in X .

An intuitionistic fuzzy set A in X is simply denoted by $A = \langle x, \mu_A, \nu_A \rangle$ instead of denoting $A = \{ \langle x, \mu_A(x), \nu_A(x) \rangle : x \in X \}$.

Definition 2.2 [1]: Let A and B be two IFSs of the form

$$A = \{ \langle x, \mu_A(x), \nu_A(x) \rangle : x \in X \}$$

and

$$B = \{ \langle x, \mu_B(x), \nu_B(x) \rangle : x \in X \}.$$

Then,

- (a) $A \subseteq B$ if and only if $\mu_A(x) \leq \mu_B(x)$ and $\nu_A(x) \geq \nu_B(x)$ for all $x \in X$,
- (b) $A = B$ if and only if $A \subseteq B$ and $A \supseteq B$,
- (c) $A^c = \{ \langle x, \nu_A(x), \mu_A(x) \rangle : x \in X \}$,
- (d) $A \cup B = \{ \langle x, \mu_A(x) \vee \mu_B(x), \nu_A(x) \wedge \nu_B(x) \rangle : x \in X \}$,
- (e) $A \cap B = \{ \langle x, \mu_A(x) \wedge \mu_B(x), \nu_A(x) \vee \nu_B(x) \rangle : x \in X \}$.

The intuitionistic fuzzy sets $0 \sim = \langle x, 0, 1 \rangle$ and $1 \sim = \langle x, 1, 0 \rangle$ are respectively the empty set and the whole set of X .

Definition 2.3 [2]: An *intuitionistic fuzzy topology* (IFT in short) on X is a family τ of IFSs in X satisfying the following axioms:

- (i) $0 \sim, 1 \sim \in \tau$,
- (ii) $G_1 \cap G_2 \in \tau$ for any $G_1, G_2 \in \tau$,

(iii) $\cup G_i \in \tau$ for any family $\{G_i : i \in J\} \subseteq \tau$.

In this case the pair (X, τ) is called *intuitionistic fuzzy topological space* (IFTS in short) and any IFS in τ is known as an *intuitionistic fuzzy open set* (IFOS in short) in X . The complement A^c of an IFOS A in an IFTS (X, τ) is called an *intuitionistic fuzzy closed set* (IFCS in short) in X .

Definition 2.4 [5]: An IFS A in an IFTS (X, τ) is said to be an *intuitionistic fuzzy β generalized closed set* (IF β GCS for short) if $\beta\text{cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is an IF β OS in (X, τ) .

Definition 2.5 [7]: A mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is called an *intuitionistic fuzzy β generalized continuous* (IF β G continuous for short) **mapping** if $f^{-1}(V)$ is an IF β GCS in (X, τ) for every IFCS V of (Y, σ) .

Definition 2.6 [8] : A mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is said to be an *intuitionistic fuzzy almost β generalized continuous* (IFa β G continuous for short) **mapping** if $f^{-1}(A)$ is an IF β GCS in X for every IFRCS A in Y .

Definition 2.7 [9]: A mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is said to be an *intuitionistic fuzzy completely β generalized continuous* (IF completely β G continuous for short) **mapping** if $f^{-1}(V)$ is an IFRCS in X for every IF β GCS V in Y .

Definition 2.8 [10] : A mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is said to be an *intuitionistic fuzzy weakly β generalized continuous* (IFW β G continuous for short) **mapping** if $f^{-1}(V) \subseteq \beta\text{gint}(f^{-1}(\text{cl}(V)))$ for each IFOS V in Y .

Definition 2.9 [4]: A mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is said to be an *perfectly continuous* if $f^{-1}(V)$ is clopen in X for every open set $V \subset Y$.

III. PERFECTLY β GENERALIZED CONTINUOUS MAPPINGS IN INTUITIONISTIC FUZZY TOPOLOGICAL SPACES

In this section we introduce intuitionistic fuzzy perfectly β generalized continuous mappings and study some of their properties.

Definition 3.1: A mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is said to be an *intuitionistic fuzzy perfectly β generalized continuous* (IFp β G continuous for short) **mapping** if $f^{-1}(A)$ is clopen in (X, τ) for every IF β GCS A of (Y, σ) .

Theorem 3.2: Every IF β G continuous mapping is an IF continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF β G continuous mapping. Let A be an IFCS in Y . Since every IFCS is an IF β GCS [5], A is an IF β GCS in Y . Since f is an IF β G continuous mapping, $f^{-1}(A)$ is an IF clopen in X . Thus $f^{-1}(A)$ is an IFCS in X . Hence f is an IF continuous mapping.

Example 3.3: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.4_b), (0.5_a, 0.6_b) \rangle$, $G_2 = \langle y, (0.5_u, 0.4_v), (0.5_u, 0.6_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $\text{IF}\beta\text{C}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{O}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{C}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$\text{IF}\beta\text{O}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

The IFS $A = \langle y, (0.5_u, 0.6_v), (0.5_u, 0.4_v) \rangle$ is an IFCS in Y . Then $f^{-1}(A)$ is an IFCS in X . Therefore f is an IF continuous mapping, but not an IF β G continuous mapping. Since for an IF β GCS $A = \langle y, (0.5_u, 0.6_v), (0.5_u, 0.4_v) \rangle$ in Y , and $f^{-1}(A)$ is not an IF clopen in X , as $\text{cl}(f^{-1}(A)) = G_1^c = f^{-1}(A)$ and $\text{int}(f^{-1}(A)) = G_1 \neq f^{-1}(A)$.

Theorem 3.4: Every IF β G continuous mapping is an IF α continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF β G continuous mapping. Let A be an IFCS in Y . Since every IFCS is an IF β GCS [5], A is an IF β GCS in Y . Since f is an IF β G continuous mapping, $f^{-1}(A)$ is an IF clopen in X . That is $f^{-1}(A)$ is an IFCS in X . Since every IFCS is an IF α CS, $f^{-1}(A)$ is an IF α CS in X . Hence f is an IF α continuous mapping.

Example 3.5: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.4_a, 0.3_b), (0.5_a, 0.4_b) \rangle$, $G_2 = \langle y, (0.8_u, 0.8_v), (0.2_u, 0.2_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $\text{IF}\beta\text{C}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{O}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{C}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u < 0.8 \text{ or } \mu_v < 0.8, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$\text{IF}\beta\text{O}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u > 0.2 \text{ or } \mu_v > 0.2, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

Here the mapping f is an $\text{IF}\alpha$ continuous mapping, but not an $\text{IFp}\beta\text{G}$ continuous mapping. Since for an $\text{IF}\beta\text{GCS } A = \langle y, (0.1_u, 0.2_v), (0.9_u, 0.8_v) \rangle$ in Y , $f^{-1}(A)$ is not an IF clopen in X , as $\text{cl}(f^{-1}(A)) = G_1^c \neq f^{-1}(A)$ and $\text{int}(f^{-1}(A)) = 0_{\sim} \neq f^{-1}(A)$.

Theorem 3.6: Every $\text{IFp}\beta\text{G}$ continuous mapping is an IFS continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an $\text{IFp}\beta\text{G}$ continuous mapping. Let A be an IFCS in Y . Since every IFCS is an $\text{IF}\beta\text{GCS}$ [5], A is an $\text{IF}\beta\text{GCS}$ in Y . Since f is an $\text{IFp}\beta\text{G}$ continuous mapping, $f^{-1}(A)$ is an IF clopen in X . That is $f^{-1}(A)$ is an IFCS in X . Since every IFCS is an IFSCS, $f^{-1}(A)$ is an IFSCS in X . Hence f is an IFS continuous mapping.

Example 3.7: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.6_a, 0.8_b), (0.4_a, 0.2_b) \rangle$, $G_2 = \langle y, (0.6_u, 0.8_v), (0.4_u, 0.2_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $\text{IF}\beta\text{C}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / \text{either } \mu_a < 0.6 \text{ or } \mu_b < 0.8, 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{O}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / \text{either } \mu_a > 0.4 \text{ or } \mu_b > 0.2, 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{C}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u < 0.6 \text{ or } \mu_v < 0.8, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$\text{IF}\beta\text{O}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u > 0.4 \text{ or } \mu_v > 0.2, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

Here the mapping f is an IFS continuous mapping, but f is not an IF β G continuous mapping. Since for an IF β GCS $A = \langle y, (0.1_u, 0.2_v), (0.9_u, 0.8_v) \rangle$ in Y , $f^{-1}(A)$ is not an IF clopen in X . As $\text{cl}(f^{-1}(A)) = G_1^c \neq f^{-1}(A)$ and $\text{int}(f^{-1}(A)) = 0_{\sim} \neq f^{-1}(A)$.

Theorem 3.8: Every IF β G continuous mapping is an IFP continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF β G continuous mapping. Let A be an IFCS in Y . Since every IFCS is an IF β GCS [5], A is an IF β GCS in Y . Since f is an IF β G continuous mapping, $f^{-1}(A)$ is an IF clopen in X . That is $f^{-1}(A)$ is an IFCS in X . Since every IFCS is an IFPCS, $f^{-1}(A)$ is an IFPCS in X . Hence f is an IFP continuous mapping.

Example 3.9: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.2_b), (0.4_a, 0.4_b) \rangle$, $G_2 = \langle y, (0.2_u, 0.6_v), (0.3_u, 0.4_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $\text{IF}\beta\text{C}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / \text{either } \mu_a < 0.5 \text{ or } \mu_b < 0.2, 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{O}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / \text{either } \mu_a > 0.4 \text{ or } \mu_b > 0.4, 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{C}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u < 0.2 \text{ or } \mu_v < 0.6, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$\text{IF}\beta\text{O}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u > 0.3 \text{ or } \mu_v > 0.4, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

Here the mapping f is an IFP continuous mapping, but not an IF β G continuous mapping. Since for an IF β GCS $A = \langle y, (0.2_u, 0.2_v), (0.7_u, 0.8_v) \rangle$ in Y , $f^{-1}(A)$ is not an IF clopen in X , as $\text{cl}(f^{-1}(A)) = G_1^c \neq f^{-1}(A)$ and $\text{int}(f^{-1}(A)) = 0_{\sim} \neq f^{-1}(A)$.

Theorem 3.10: Every IF β G continuous mapping is an IF β continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF β G continuous mapping. Let A be an IFCS in Y . Since every IFCS is an IF β GCS [5], A is an IF β GCS in Y . Since f is an IF β G continuous mapping, $f^{-1}(A)$ is an IF clopen in X . That is $f^{-1}(A)$ is an IFCS in X .

Since every IFCS is an IF β CS, $f^{-1}(A)$ is an IF β CS in X . Hence f is an IF β continuous mapping.

Example 3.11: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.4_b), (0.5_a, 0.6_b) \rangle$, $G_2 = \langle y, (0.6_u, 0.7_v), (0.4_u, 0.3_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $IF\beta C(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$IF\beta O(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$IF\beta C(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u < 0.6 \text{ or } \mu_v < 0.7, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$IF\beta O(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / \text{either } \mu_u > 0.4 \text{ or } \mu_v > 0.3, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

Here the mapping f is an IF β continuous mapping, but not an IF $p\beta G$ continuous mapping. Since for an IF βGCS $A = \langle y, (0.5_u, 0.2_v), (0.5_u, 0.8_v) \rangle$ in Y , $f^{-1}(A)$ is not an IF clopen in X , as $cl(f^{-1}(A)) = G_1^c \neq f^{-1}(A)$ and $int(f^{-1}(A)) = 0_{\sim} \neq f^{-1}(A)$.

Theorem 3.12: Every IF $p\beta G$ continuous mapping is an IF βG continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF $p\beta G$ continuous mapping. Let A be an IFCS in Y . Since every IFCS is an IF βGCS [5], A is an IF βGCS in Y . Since f is an IF $p\beta G$ continuous mapping, $f^{-1}(A)$ is an IF clopen in X . Thus $f^{-1}(A)$ is an IFCS in X . Since every IFCS is an IF βGCS , $f^{-1}(A)$ is an IF βGCS in X . Hence f is an IF βG continuous mapping.

Example 3.13: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.4_b), (0.5_a, 0.6_b) \rangle$, $G_2 = \langle y, (0.6_u, 0.7_v), (0.4_u, 0.3_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $IF\beta C(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$IF\beta O(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{C}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] \text{ / either } \mu_u < 0.6 \text{ or } \mu_v < 0.7, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$\text{IF}\beta\text{O}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] \text{ / either } \mu_u > 0.4 \text{ or } \mu_v > 0.3, 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

Now $G_2^c = \langle y, (0.4_u, 0.3_v), (0.6_u, 0.7_v) \rangle$ is an IFCS in Y . We have $f^{-1}(G_2^c) = \langle x, (0.4_a, 0.3_b), (0.6_a, 0.7_b) \rangle$ is an IFS in X . Now $f^{-1}(G_2^c) \subseteq G_1$. As $\beta\text{cl}(f^{-1}(G_2^c)) = f^{-1}(G_2^c) \subseteq G_1$, $f^{-1}(G_2^c)$ is an IF β GCS in X . Thus f is an IF β G continuous mapping. But f is not an IFp β G continuous mapping. Since for an IF β GCS $B = \langle y, (0.5_u, 0.2_v), (0.5_u, 0.8_v) \rangle$ in Y , and $f^{-1}(B)$ is not an IF clopen in X , as $\text{cl}(f^{-1}(B)) = G_1^c \neq f^{-1}(B)$ and $\text{int}(f^{-1}(B)) = 0_{\sim} \neq f^{-1}(B)$.

Theorem 3.14: Every IFp β G continuous mapping is an IFa β G continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IFp β G continuous mapping. Let A be an IFRCS in Y . Since every IFRCS is an IF β GCS [5], A is an IF β GCS in Y . By hypothesis, $f^{-1}(A)$ is an IF clopen in X . Thus $f^{-1}(A)$ is an IFCS in X . Since every IFCS is an IF β GCS, $f^{-1}(A)$ is an IF β GCS in X . Hence f is an IFa β G continuous mapping.

Example 3.15: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.4_b), (0.5_a, 0.6_b) \rangle$, $G_2 = \langle y, (0.3_u, 0.2_v), (0.7_u, 0.8_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $\text{IF}\beta\text{C}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] \text{ / } 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{O}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] \text{ / } 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{C}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] \text{ / } 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$\text{IF}\beta\text{O}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] \text{ / } 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

Now $G_2^c = \langle y, (0.7_u, 0.8_v), (0.3_u, 0.2_v) \rangle$ is an IFRCS in Y . Since $\text{cl}(\text{int}(G_2^c)) = \text{cl}(G_2) = G_2^c$. We have $f^{-1}(G_2^c) = \langle x, (0.7_a, 0.8_b), (0.3_a, 0.2_b) \rangle$ is an IFS in X . Now $f^{-1}(G_2^c) \subseteq 1_{\sim}$. As $\beta\text{cl}(f^{-1}(G_2^c)) = f^{-1}(G_2^c) \subseteq 1_{\sim}$, $f^{-1}(G_2^c)$ is an IF β GCS in X . Thus f is an IFa β G continuous mapping. But f is not an IFp β G continuous mapping. Since

for an IF β GCS $B = \langle y, (0.5_u, 0.3_v), (0.2_u, 0.1_v) \rangle$ in Y and $f^{-1}(B)$ is not an IF clopen in X , as $\text{cl}(f^{-1}(B)) = 1_{\sim} \neq f^{-1}(B)$ and $\text{int}(f^{-1}(B)) = 0_{\sim} \neq f^{-1}(B)$.

Theorem 3.16: Every IF β G continuous mapping is an IFW β G continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF β G continuous mapping. Let A be an IFOS in Y . Then A is an IF β GOS in Y . Since f is an IF β G continuous mapping, $f^{-1}(A)$ is an IFclopen in X . Now $f^{-1}(A) = \text{int}(f^{-1}(A)) \subseteq \beta\text{gint}(f^{-1}(A)) = \beta\text{gint}(\text{cl}(f^{-1}(A)))$. Thus $f^{-1}(A) = \text{cl}(f^{-1}(A))$. This implies $f^{-1}(A) \subseteq \beta\text{gint}(\text{cl}(f^{-1}(A)))$. Hence f is an IFW β G continuous mapping.

Example 3.17: Let $X = \{a, b\}$, $Y = \{u, v\}$ and $G_1 = \langle x, (0.5_a, 0.4_b), (0.5_a, 0.6_b) \rangle$, $G_2 = \langle y, (0.4_u, 0.3_v), (0.6_u, 0.7_v) \rangle$. Then $\tau = \{0_{\sim}, G_1, 1_{\sim}\}$ and $\sigma = \{0_{\sim}, G_2, 1_{\sim}\}$ are IFTs on X and Y respectively. Define a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = u$ and $f(b) = v$.

Then, $\text{IF}\beta\text{C}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{O}(X) = \{0_{\sim}, 1_{\sim}, \mu_a \in [0,1], \mu_b \in [0,1], \nu_a \in [0,1], \nu_b \in [0,1] / 0 \leq \mu_a + \nu_a \leq 1 \text{ and } 0 \leq \mu_b + \nu_b \leq 1\}$,

$\text{IF}\beta\text{C}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$,

$\text{IF}\beta\text{O}(Y) = \{0_{\sim}, 1_{\sim}, \mu_u \in [0,1], \mu_v \in [0,1], \nu_u \in [0,1], \nu_v \in [0,1] / 0 \leq \mu_u + \nu_u \leq 1 \text{ and } 0 \leq \mu_v + \nu_v \leq 1\}$.

The IFS $G_2 = \langle y, (0.4_u, 0.3_v), (0.6_u, 0.7_v) \rangle$ is an IFOS in Y . Now $G_2^c = \langle y, (0.6_u, 0.7_v), (0.4_u, 0.3_v) \rangle$ is an IFCS in Y .

We have $\beta\text{gint}(f^{-1}(\text{cl}(G_2))) = \langle x, (0.6_a, 0.7_b), (0.4_a, 0.3_b) \rangle$. Hence $f^{-1}(G_2) \subseteq \beta\text{gint}(f^{-1}(\text{cl}(G_2)))$. Therefore f is an IFW β G continuous mapping. But f is not an IF β G continuous mapping. Since the IFS $B = \langle y, (0.5_u, 0.3_v), (0.2_u, 0.1_v) \rangle$ is an IF β GCS in Y , but $f^{-1}(B)$ is not an IF clopen in X . As $\text{cl}(f^{-1}(B)) = 1_{\sim} \neq f^{-1}(B)$ and $\text{int}(f^{-1}(B)) = 0_{\sim} \neq f^{-1}(B)$.

Theorem 3.18: Every IF β G continuous mapping is an IF completely β G continuous mapping but not conversely in general.

Proof: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF β G continuous mapping. Let A be an IF β GCS in Y . By hypothesis, $f^{-1}(A)$ is an intuitionistic fuzzy clopen in X . Therefore

$\text{cl}(f^{-1}(A)) = f^{-1}(A)$ and $\text{int}(f^{-1}(A)) = f^{-1}(A)$. Now $\text{cl}(\text{int}(f^{-1}(A))) = \text{cl}(f^{-1}(A)) = f^{-1}(A)$. Therefore $f^{-1}(A)$ is an IFRCS in X . Hence f is an IF completely β G continuous mapping.

Theorem 3.19: A mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is an IF β G continuous mapping if and only if the inverse image of each IF β GOS [6] in Y is an intuitionistic fuzzy clopen in X .

Proof: Necessity: Let a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ be IF β G continuous mapping. Let A be an IF β GOS in Y . Then A^c is an IF β GCS in Y . Since f is an IF β G continuous mapping, $f^{-1}(A^c)$ is IF clopen in X . As $f^{-1}(A^c) = (f^{-1}(A))^c$, we have $f^{-1}(A)$ is IF clopen in X .

Sufficiency: Let B be an IF β GCS in Y . Then B^c is an IF β GOS in Y . By hypothesis, $f^{-1}(B^c)$ is IF clopen in X . Which implies $f^{-1}(B)$ is IF clopen in X , as $f^{-1}(B^c) = (f^{-1}(B))^c$. Therefore f is an IF β G continuous mapping.

Theorem 3.20: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF continuous mapping and $g: (Y, \sigma) \rightarrow (Z, \delta)$ is IF β G continuous mapping, then $g \circ f: (X, \tau) \rightarrow (Z, \delta)$ is an IF β G continuous mapping.

Proof: Let A be an IF β GCS in Z . Since g is an IF β G continuous mapping, $g^{-1}(A)$ is an IF clopen in Y . Since f is an IF continuous mapping, $f^{-1}(g^{-1}(A))$ is an IFCS in X , as well as IFOS in X . Hence $g \circ f$ is an IF β G continuous mapping.

Theorem 3.21: The composition of two IF β G continuous mapping is an IF β G continuous mapping in general.

Proof: Let $f: X \rightarrow Y$ and $g: Y \rightarrow Z$ be any two IF β G continuous mappings. Let A be an IF β GCS in Z . By hypothesis, $g^{-1}(A)$ is IF clopen in Y and hence an IFCS in Y . Since every IFCS is an IF β GCS, $g^{-1}(A)$ is an IF β GCS in Y . Further, since f is an IF β G continuous mapping, $f^{-1}(g^{-1}(A)) = (g \circ f)^{-1}(A)$ is IF clopen in X . Hence $g \circ f$ is an IF β G continuous mapping.

Theorem 3.22: Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an IF β G continuous mapping and $g: (Y, \sigma) \rightarrow (Z, \delta)$ is an IF β G irresolute mapping [9], then $g \circ f: (X, \tau) \rightarrow (Z, \delta)$ is an IF β G continuous mapping.

Proof: Let A be an IF β GCS in Z . By hypothesis, $g^{-1}(A)$ is an IF β GCS in Y . Since f is an IF β G continuous mapping, $f^{-1}(g^{-1}(A)) = (g \circ f)^{-1}(A)$ is IF clopen in X . Hence $g \circ f$ is an IF β G continuous mapping.

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